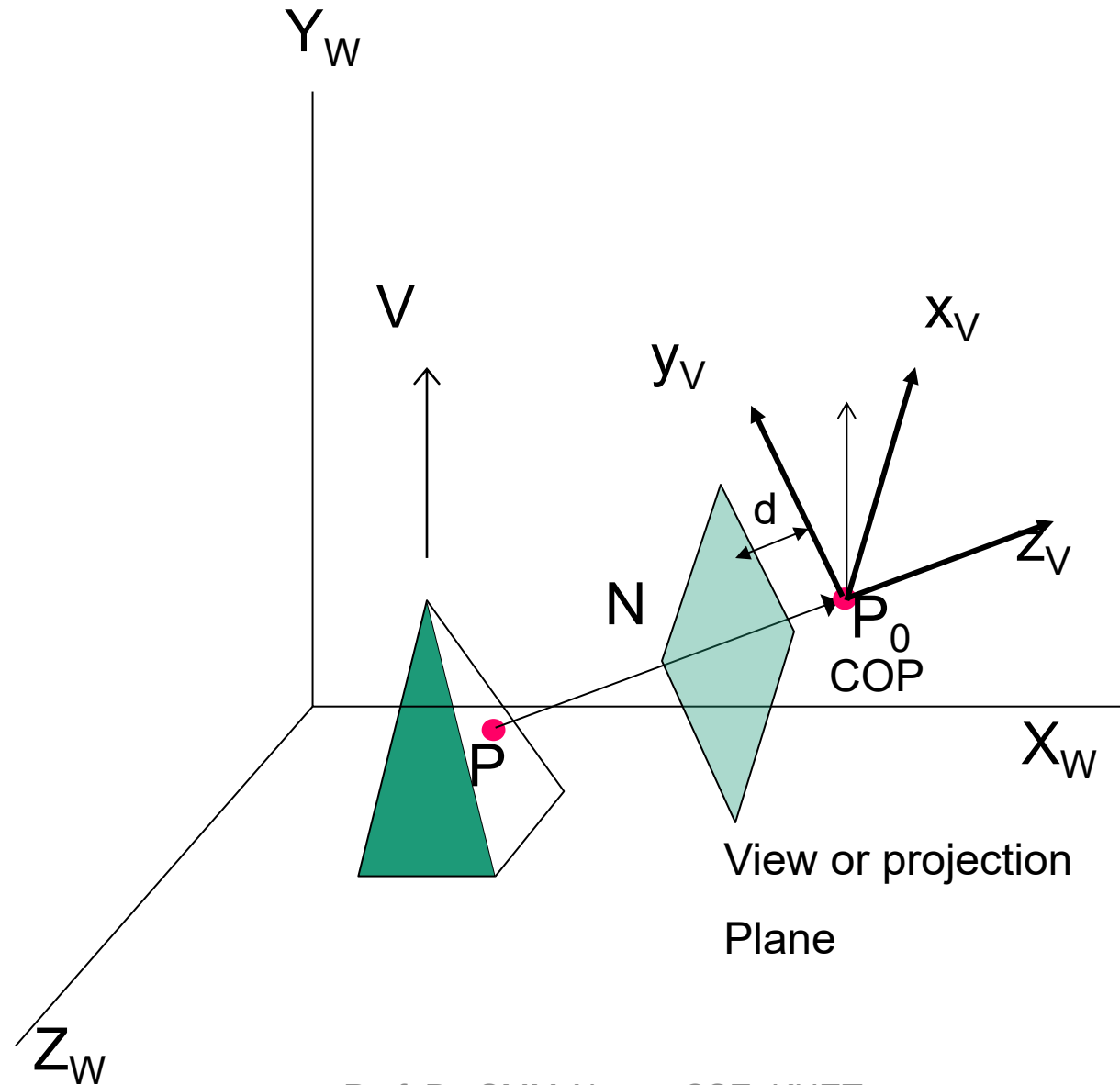


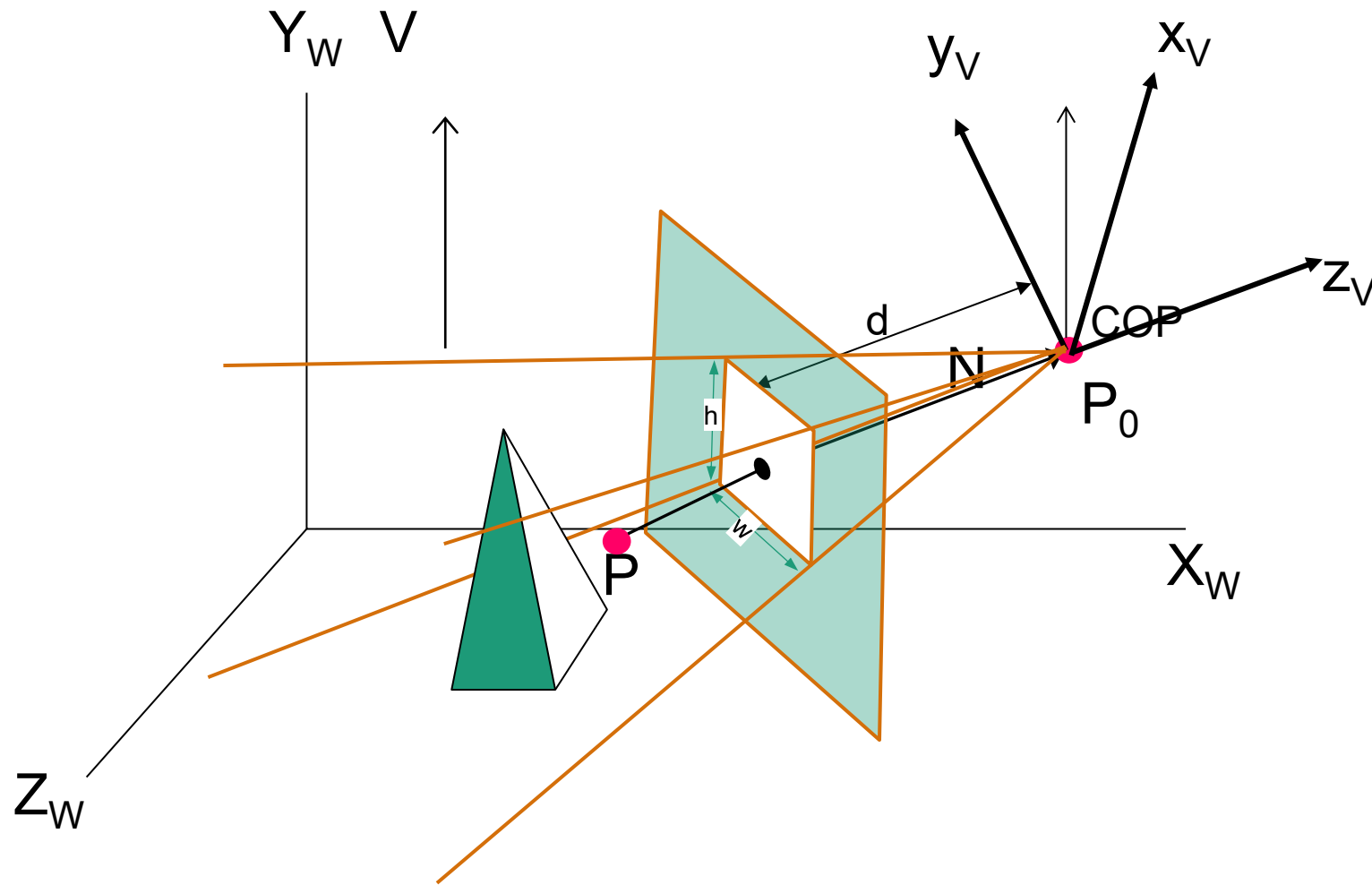
Projective Transformation

Amartya Kundu Durjoy
Lecturer, CSE, UGV

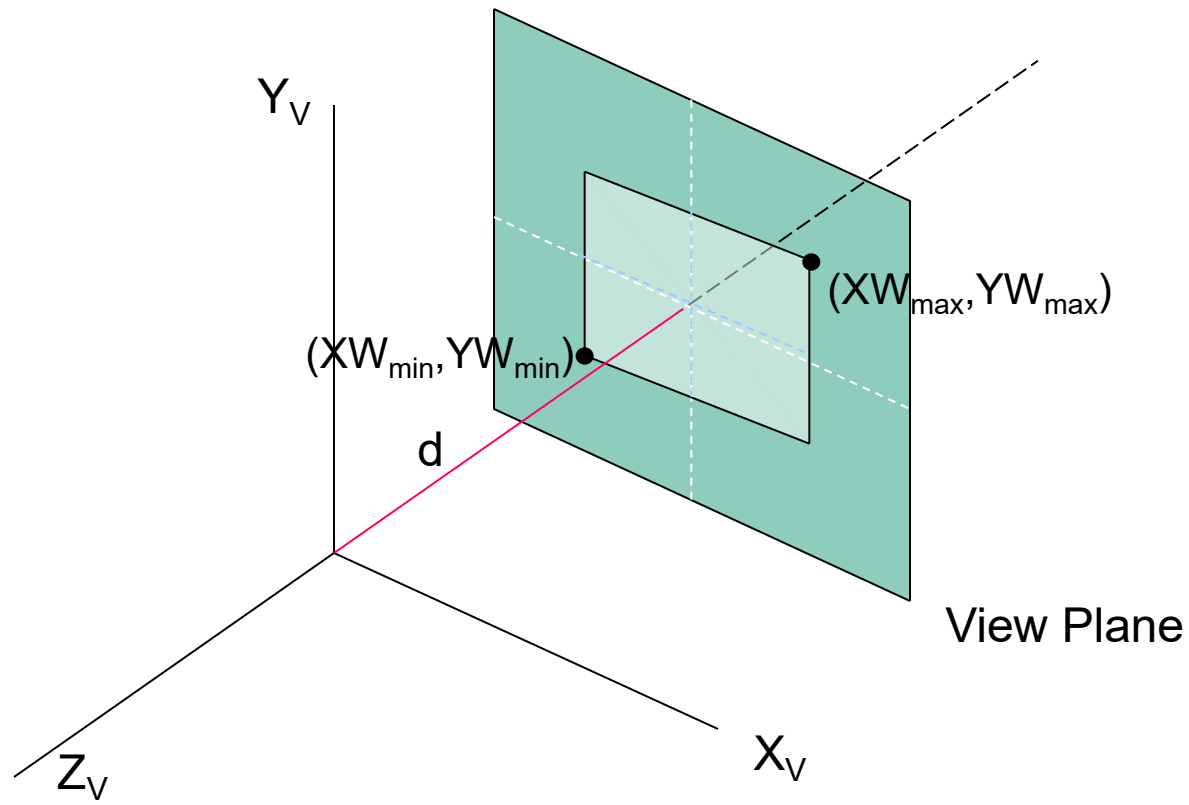
WCS, VCS and projection



View Window



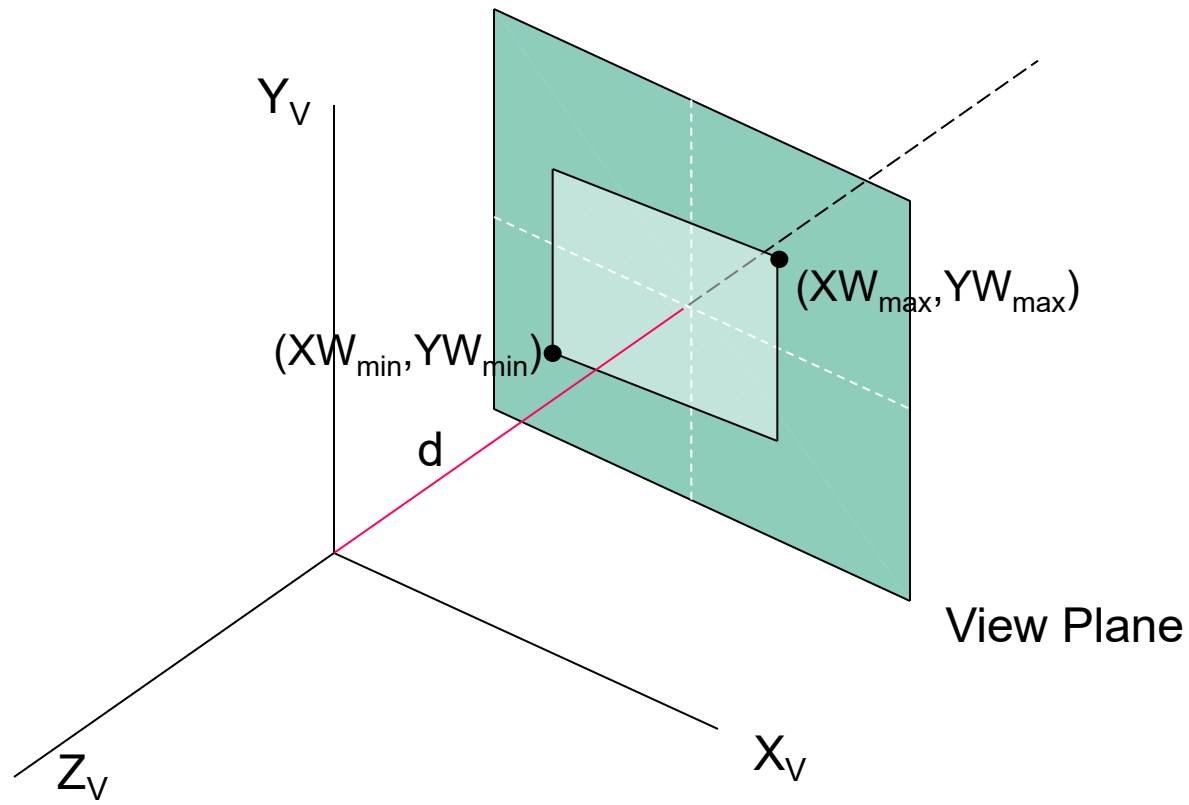
View Window - symmetric



$$XW_{max} = -XW_{min},$$

$$YW_{max} = -YW_{min}$$

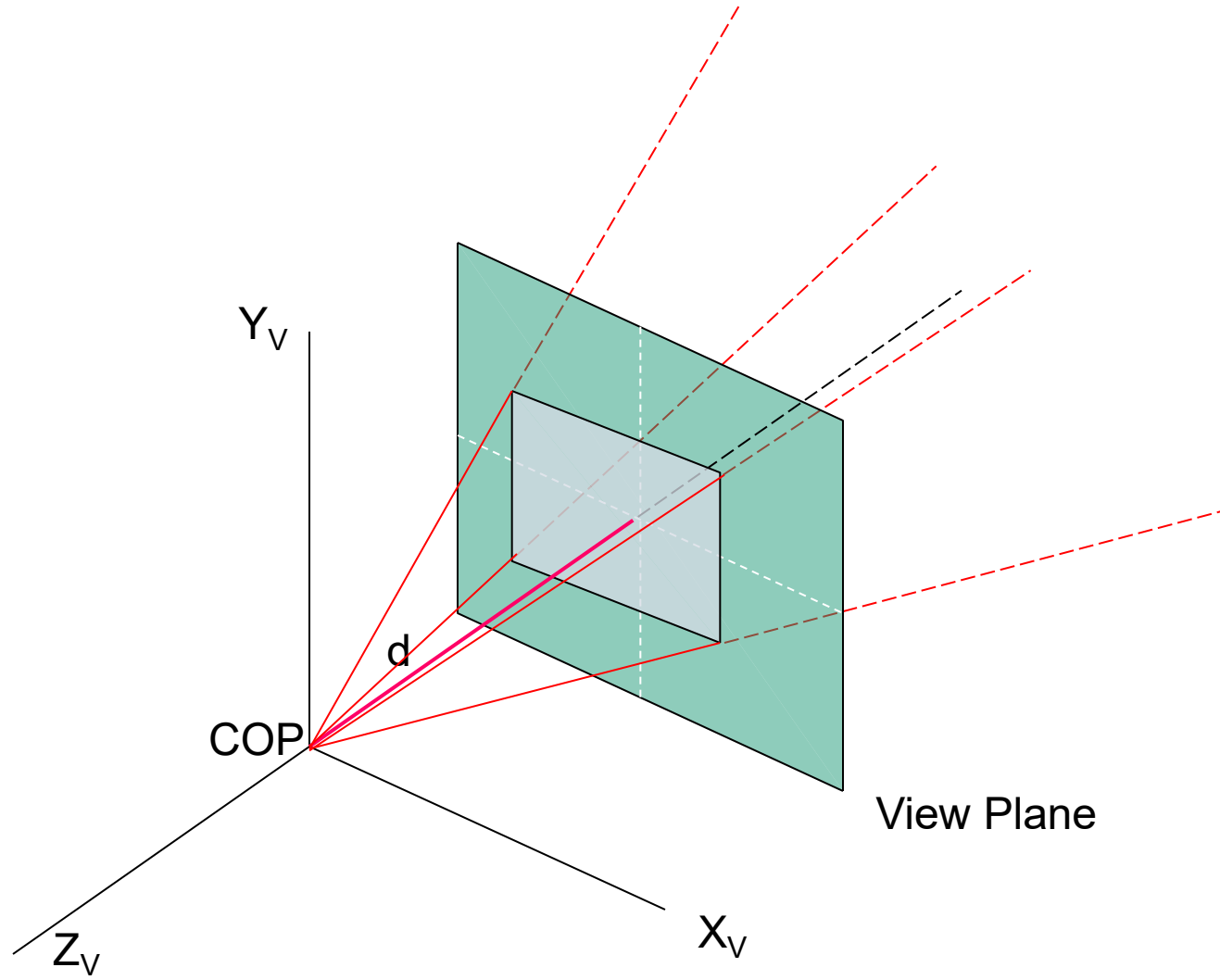
View Window - asymmetric



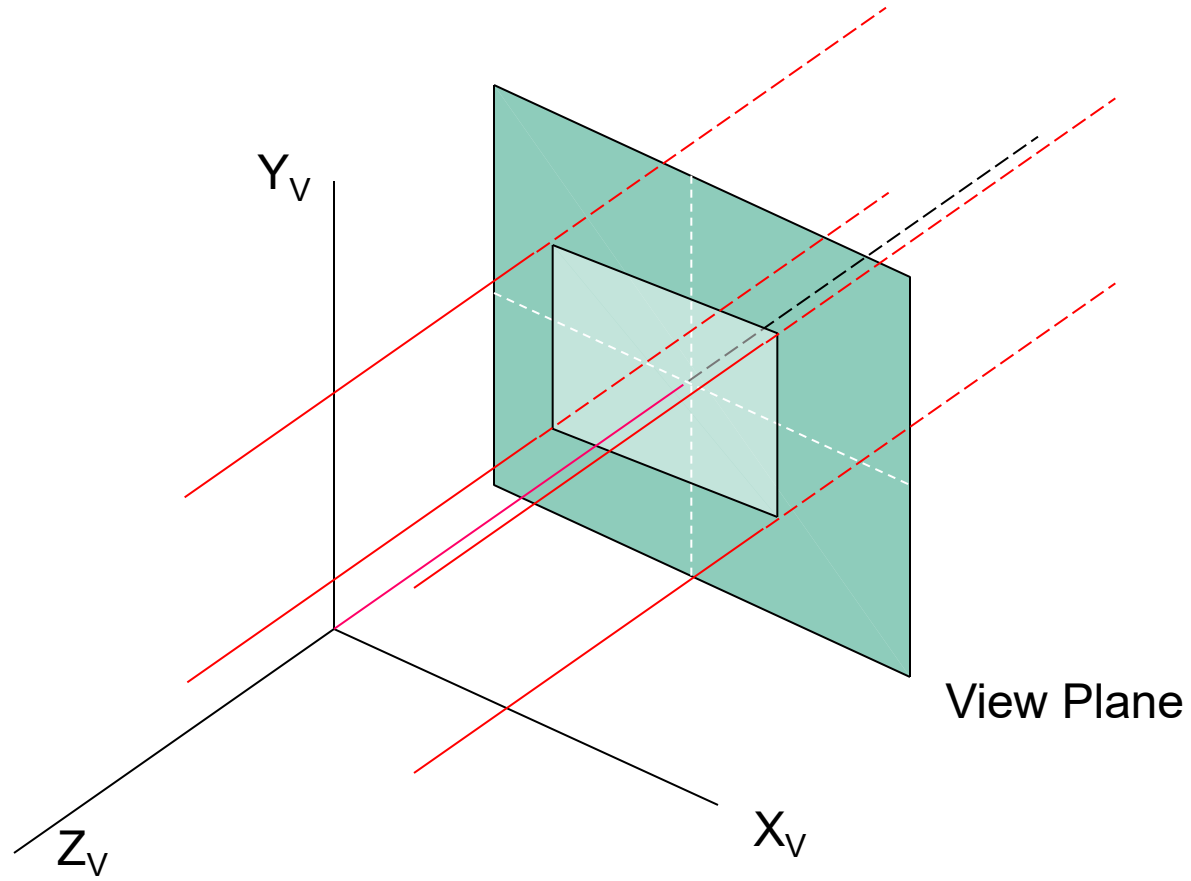
$$XW_{max} \neq -XW_{min},$$

$$YW_{max} \neq -YW_{min}$$

View Volume - Perspective



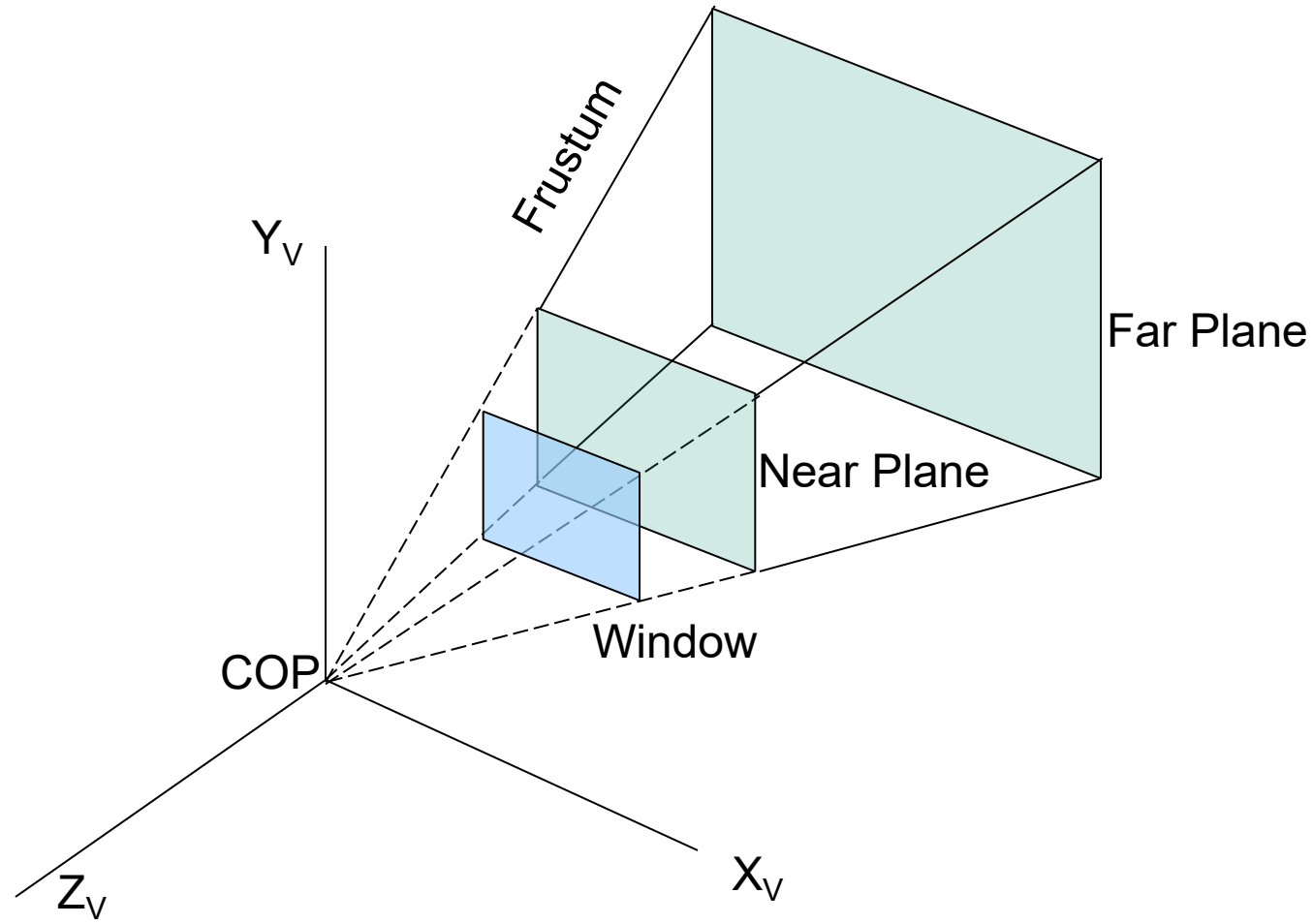
View Volume – Orthographic Projection



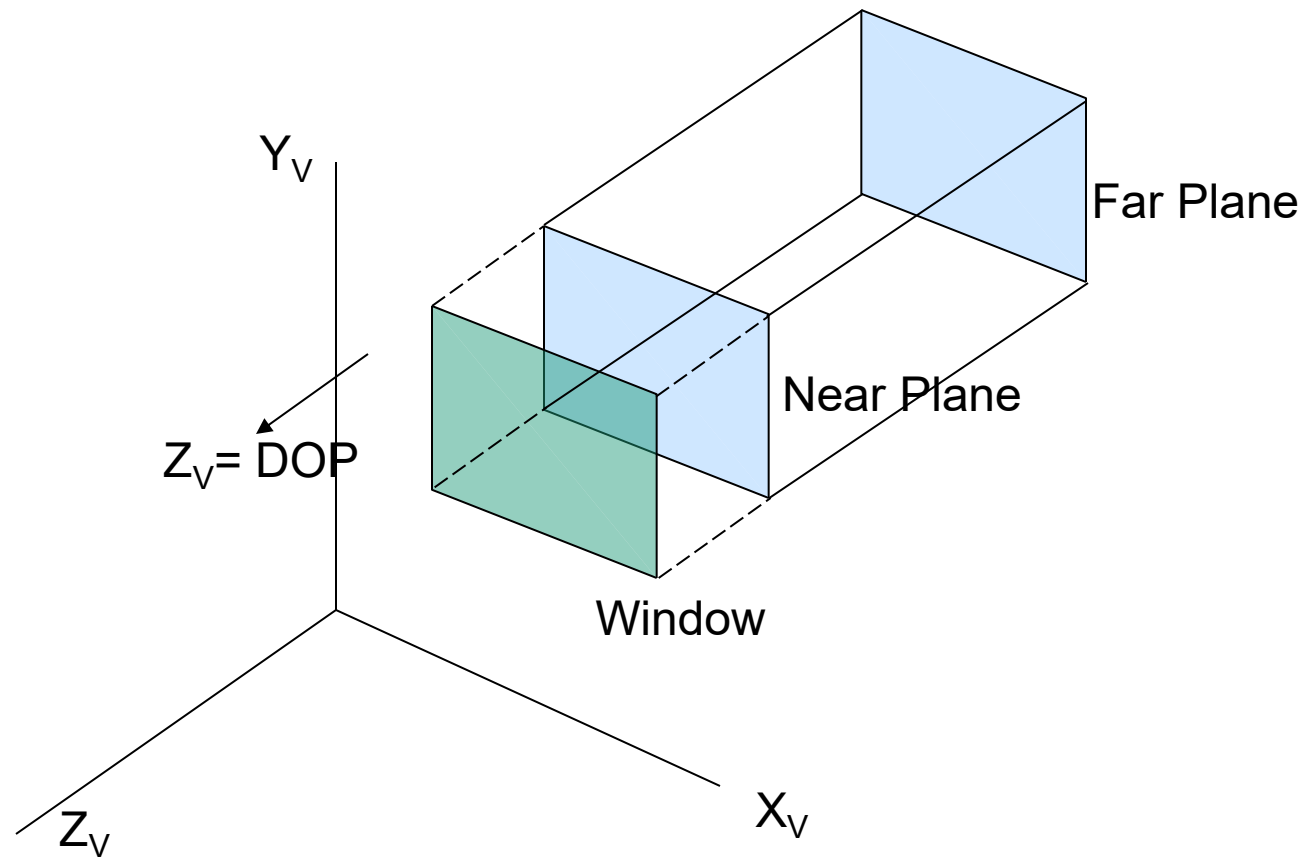
View Volume

- ❑ Finite \sim is obtained by limiting the extent of volume in Z_v direction
- ❑ Two plane parallel to view plane are used for this purpose, planes are –
 - **Near / Front plane** and **Far / Back plane**
 - Both must be same side of COP
- ❑ Adv. of using **Near, Far plane**
 - These planes eliminates parts of the scene from viewing operation based on depth.
 - Special adv. in case of perspective projection

Finite View Volume - Perspective

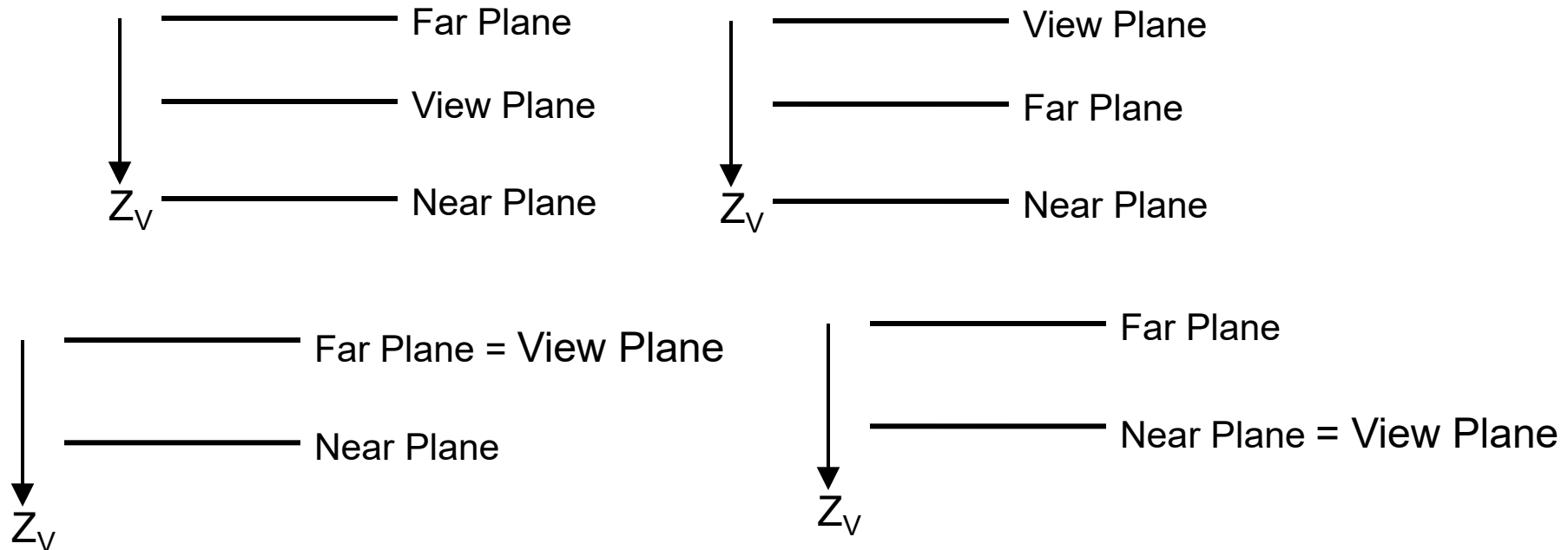


Finite View Volume – Orthographic Projection



Relative placement

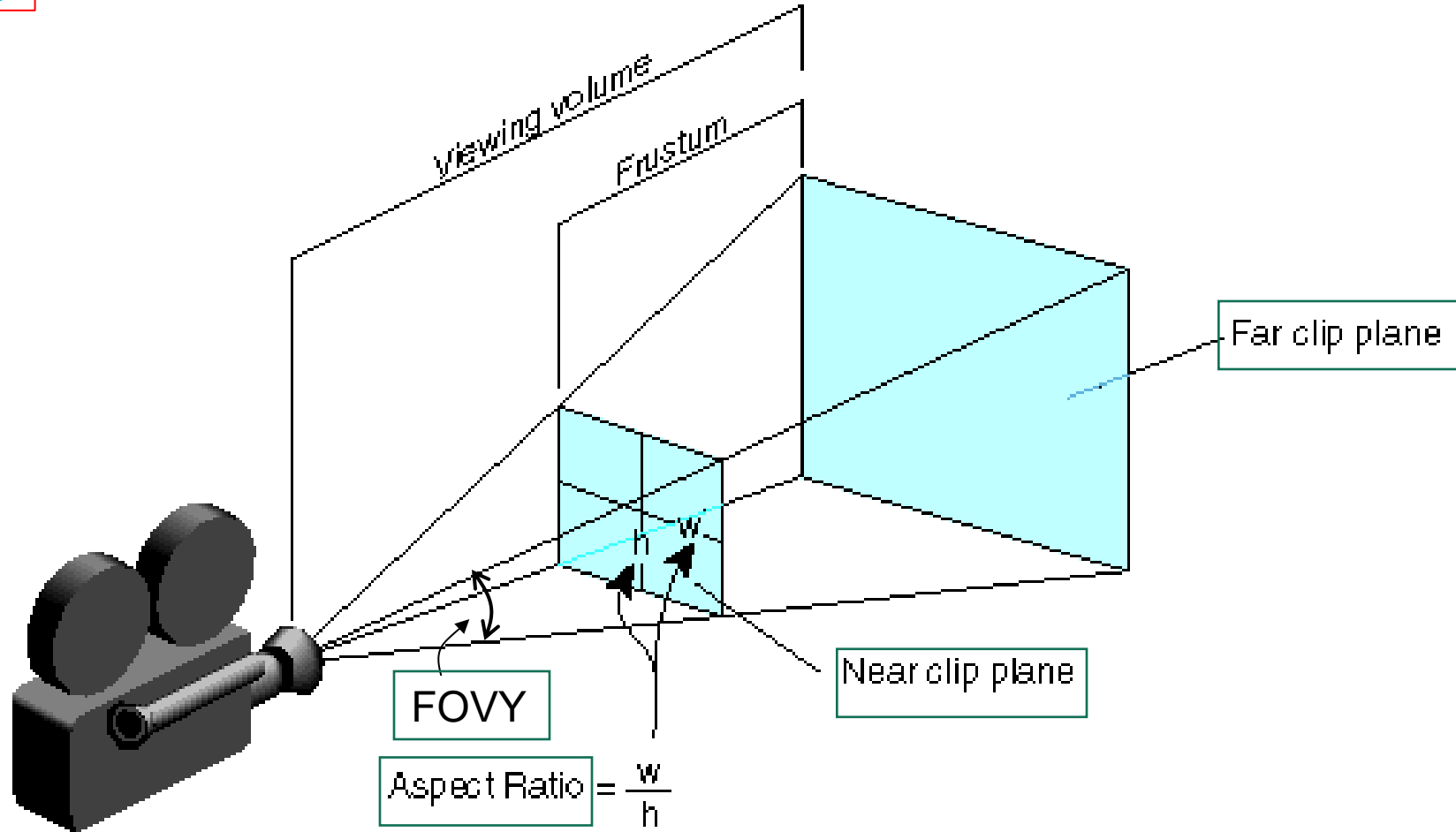
- ~ of **View, Near, Far planes** depend on
 - type of view we want &
 - limitation of Graphics package



OpenGL Uses it

Symmetric view volume - Perspective

Another way



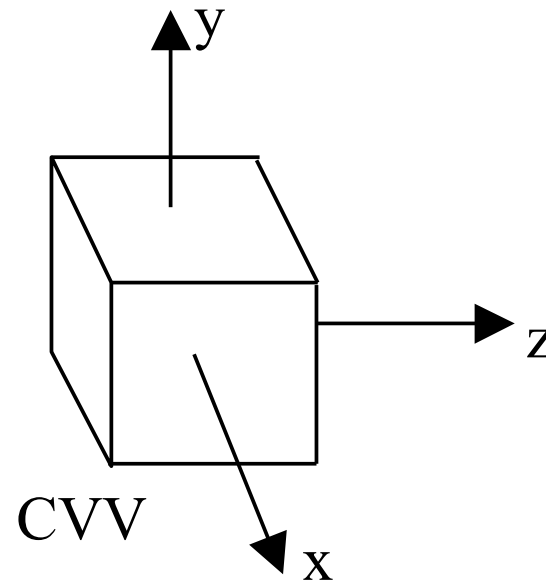
$$h = 2d * \tan(\text{fovy}/2)$$

Normalization Transformation

- ❑ Transforms VCS values to NDCS one

- ❑ Canonical View Volumes

- The 3D object model is not actually clipped inside the projection view volume.
- The view volume is instead mapped to a **canonical view volume** (CVV) which is a cube that extends from -1 to $+1$ in each dimension, having center at the origin.
- The dimensions of the CVV facilitates a fast and efficient clipping.



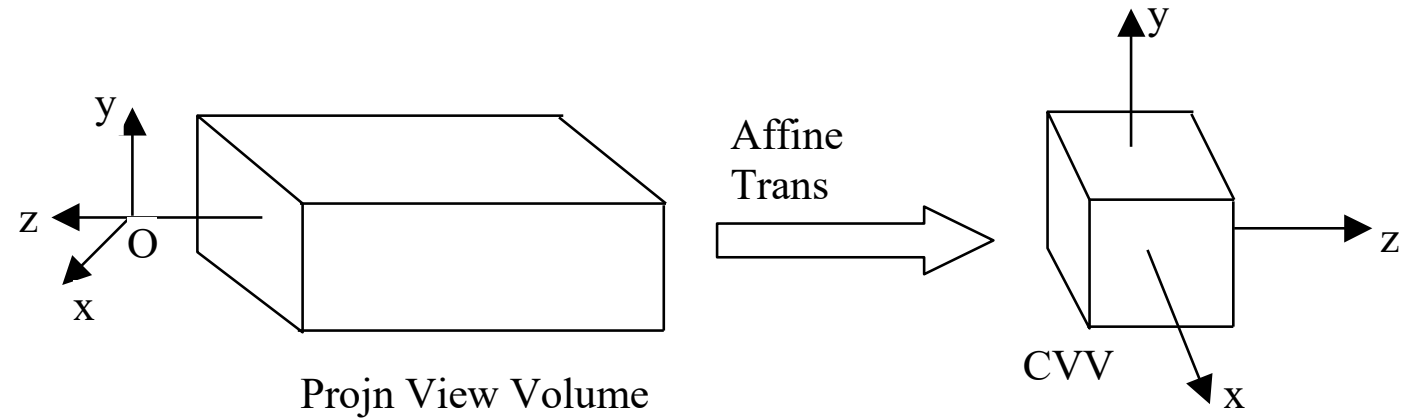
$$-1 \leq x \leq 1$$

$$-1 \leq y \leq 1$$

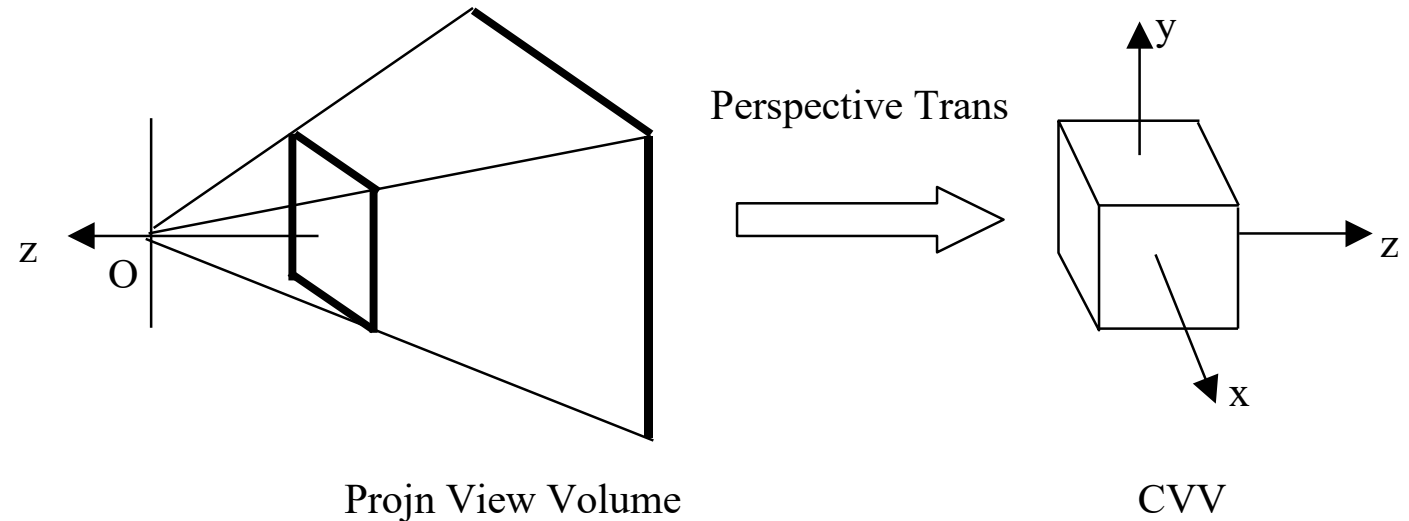
$$-1 \leq z \leq 1$$

Mapping to CVV

Orthographic:



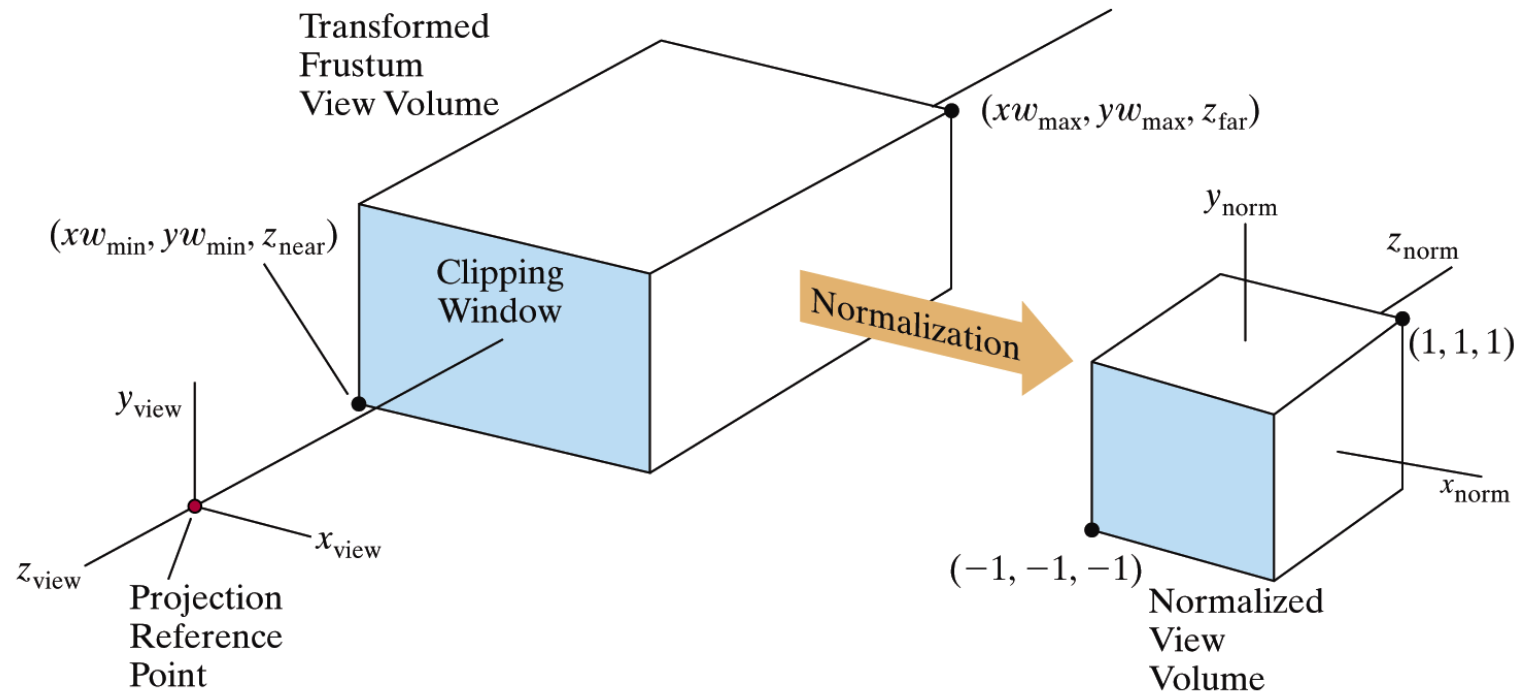
Perspective:



Normalization lets us clip against simple cube regardless of type of projection

Orthographic Transform

- ❑ The parallelepiped view volume is squeezed (scaled) around position (0, 0, 0) and the z axis is reversed

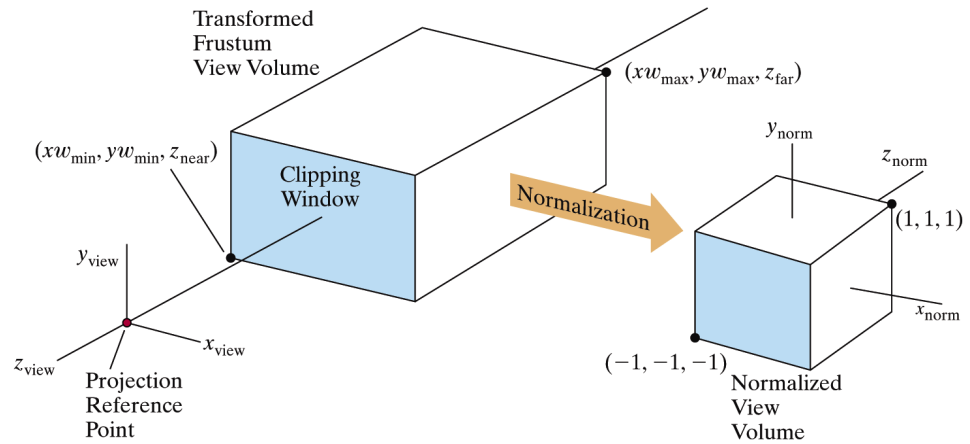


Orthographic Transform

$$T\left(-\frac{r+l}{2}, -\frac{t+b}{2}, \frac{|n|+|f|}{2}\right)$$

$$S\left(\frac{2}{r-l}, \frac{2}{t-b}, \frac{-2}{|f|-|n|}\right)$$

$$M_{orth,norm} = S.T$$



$$M_{orth,norm} = \begin{pmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{|n|-|f|} & \frac{|n|+|f|}{|n|-|f|} \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Here,

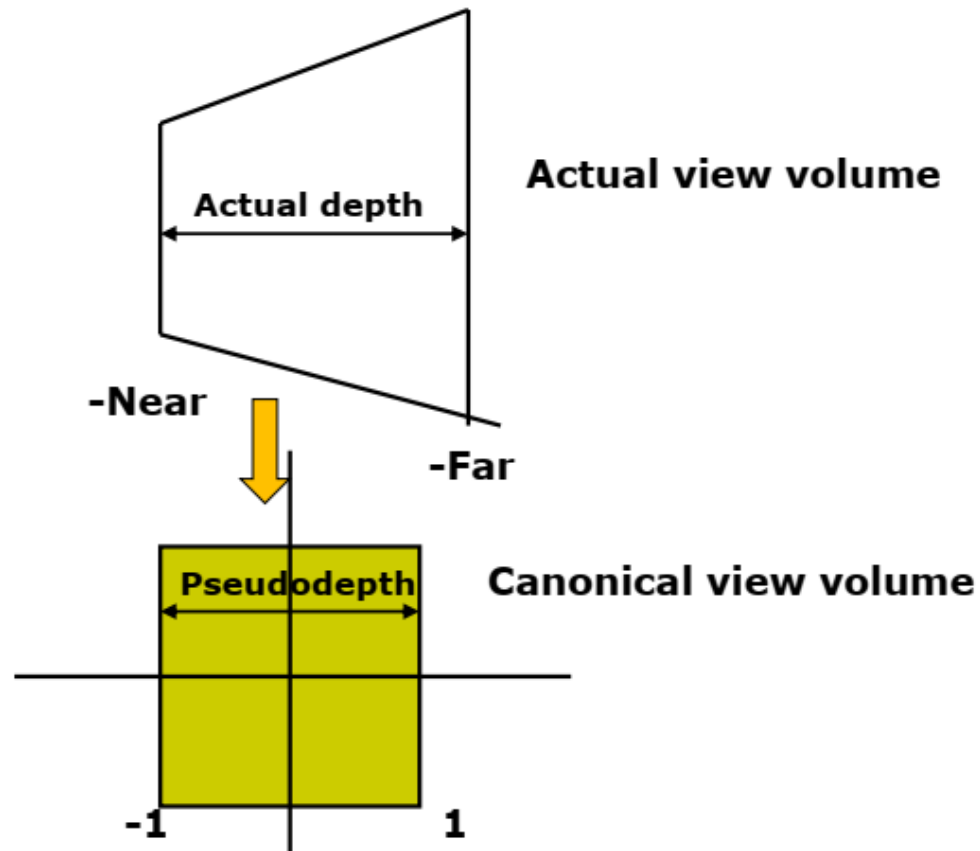
$$f < n < 0$$

Or

$$0 < |n| < |f|$$

Perspective Transform

- **Perspective transformation** maps actual z distance of perspective view volume to range $[-1 \text{ to } 1]$ (**Pseudodepth**) for canonical view volume

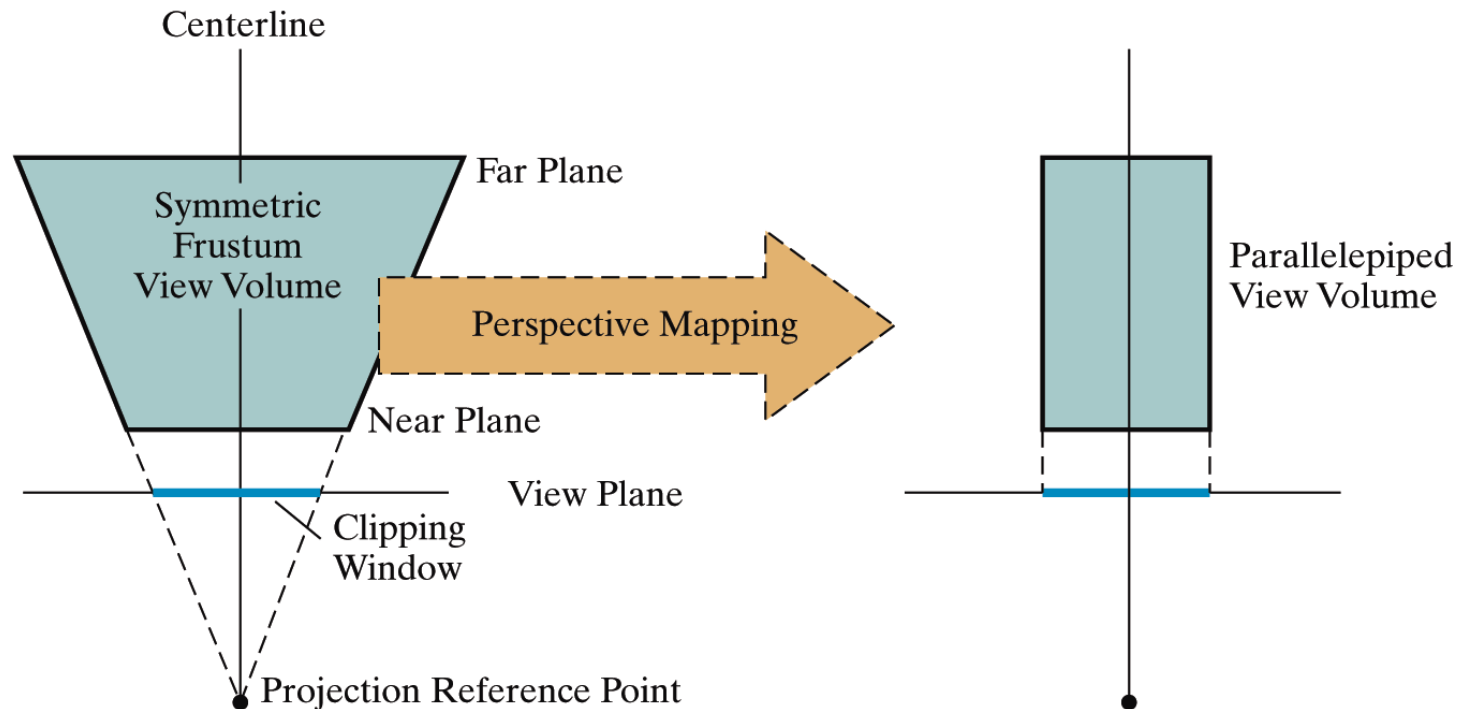


We want **perspective Transformation** and NOT classical projection!!

Set scaling z
 $\text{Pseudodepth} = az + b$
Next solve for a and b

Perspective Transform

- ❑ The frustum shaped viewing volume has been converted to a parallelepiped
 - remember we preserved all z coordinate depth information
 - How?
- ❑ And then parallelepiped volume is mapped to CVV as before



Perspective without Depth

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -\frac{1}{d} & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \\ -\frac{z}{d} \end{pmatrix}$$

$$\begin{pmatrix} x \\ y \\ z \\ -\frac{z}{d} \end{pmatrix} \xrightarrow{\text{perspective division}} \begin{pmatrix} \frac{x}{-\left(z/d\right)} \\ \frac{y}{-\left(z/d\right)} \\ -d \\ 1 \end{pmatrix}$$

- The depth information is lost as the last two components are same
- But depth information of the projected points is essential for hidden surface removal and other purposes like blending, shading etc.

Perspective with Depth

❑ Sufficient to use **pseudodepth**

- what is a good choice? Can we use z as pseudodepth? (farther point has more negative z value)
- $z' = \alpha z + \beta$ which is a linear function before perspective division

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -\frac{1}{d} & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ \alpha z + \beta \\ -\frac{z}{d} \end{pmatrix} \xrightarrow{\text{perspective division}} \begin{pmatrix} \frac{x}{-(z/d)} \\ \frac{y}{-(z/d)} \\ \frac{d(\alpha z + \beta)}{-z} \\ 1 \end{pmatrix}$$

$$z' = -d \cdot \alpha - \frac{d \cdot \beta}{z}$$

For $\beta < 0$, z' is a monotonically increasing function of *depth*.

Perspective Transform - Frustum to Parallelepiped

Rearrange the perspective transformation matrix

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -\frac{1}{d} & 0 \end{pmatrix} \cong \begin{pmatrix} |n| & 0 & 0 & 0 \\ 0 & |n| & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Perspective Transform - Frustum to Parallelepiped

Chose α, β , such a way that a point in near plane / far plane perspectively projects on near / far plane

$$\begin{pmatrix} |n| & 0 & 0 & 0 \\ 0 & |n| & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} r & rf/n \\ t & tf/n \\ -|n| & -|f| \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} |n|r & rf \\ |n|t & tf \\ -\alpha|n| + \beta & -\alpha|f| + \beta \\ |n| & |f| \end{pmatrix} = \begin{pmatrix} r & r \\ t & t \\ \frac{-\alpha|n| + \beta}{|n|} & \frac{-\alpha|f| + \beta}{|f|} \\ 1 & 1 \end{pmatrix}$$

Apply Boundary Condition

$$\begin{aligned} \frac{-\alpha|n| + \beta}{|n|} &= -|n| \\ \Rightarrow -\alpha|n| + \beta &= -|n|^2 \end{aligned}$$

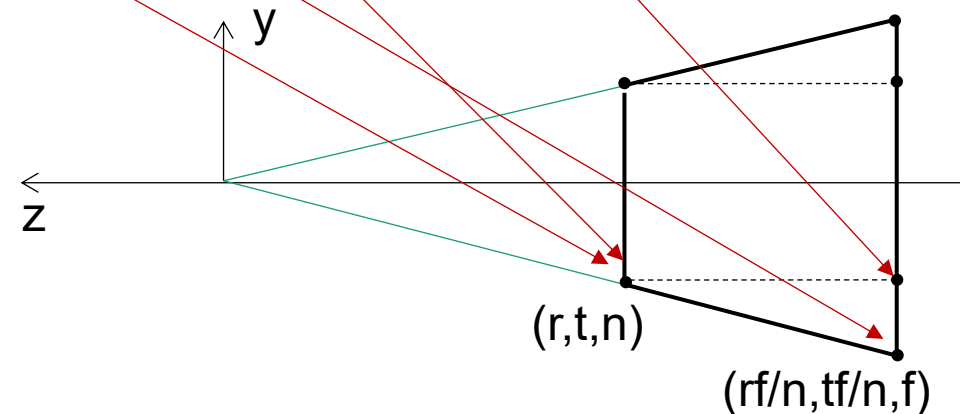
Similarly

$$-\alpha|f| + \beta = -|f|^2$$

Solving

$$\alpha = |n| + |f|$$

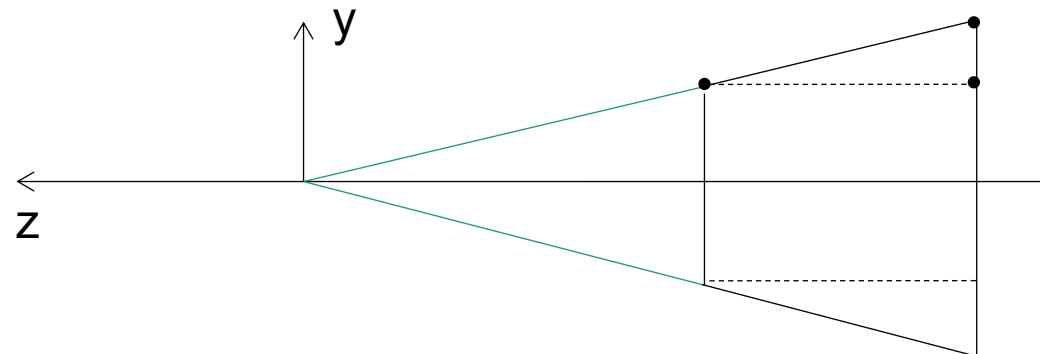
$$\beta = |n||f|$$



Perspective Transform - Parallelepiped to CVV

$$M_{per,norm} = \begin{pmatrix} \frac{2}{r-l} & 0 & 0 & -\frac{r+l}{r-l} \\ 0 & \frac{2}{t-b} & 0 & -\frac{t+b}{t-b} \\ 0 & 0 & \frac{2}{|n|-|f|} & \frac{|n|+|f|}{|n|-|f|} \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} |n| & 0 & 0 & 0 \\ 0 & |n| & 0 & 0 \\ 0 & 0 & |n|+|f| & |n||f| \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$= \begin{bmatrix} \frac{2|n|}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2|n|}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{|n|+|f|}{|n|-|f|} & \frac{2|f||n|}{|n|-|f|} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$



Perspective transform

If window is symmetric, $r = -l$ and $t = -b$, then

$$M_{per,norm} = \begin{bmatrix} \frac{2|n|}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2|n|}{t-b} & 0 & 0 \\ 0 & 0 & \frac{|n|+|f|}{|n|-|f|} & \frac{2|f||n|}{|n|-|f|} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

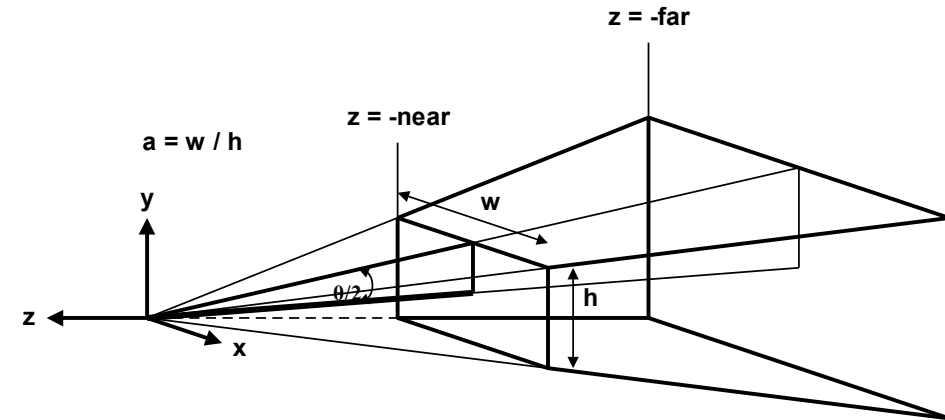
symmetric

$$M_{per,norm} = \begin{bmatrix} \frac{2|n|}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2|n|}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{|n|+|f|}{|n|-|f|} & \frac{2|f||n|}{|n|-|f|} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

Asymmetric / general

Perspective transform

$$M_{per,norm} = \begin{bmatrix} \frac{2|n|}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2|n|}{t-b} & 0 & 0 \\ 0 & 0 & \frac{|n|+|f|}{|n|-|f|} & \frac{2|f||n|}{|n|-|f|} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$



Window is symmetric, but defined by aspect ratio a , fovy θ , then

$$M_{per,norm} = \begin{bmatrix} \frac{c}{a} & 0 & 0 & 0 \\ 0 & c & 0 & 0 \\ 0 & 0 & \frac{|n|+|f|}{|n|-|f|} & \frac{2|f||n|}{|n|-|f|} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

$$c = \cot\left(\frac{\theta}{2}\right) = \frac{|n|}{t} \Rightarrow t = \frac{|n|}{c}; \quad b = -\frac{|n|}{c}$$

$$a = \frac{w}{h} = \frac{r}{t} \Rightarrow r = at = \frac{a|n|}{c}; \quad l = -\frac{a|n|}{c}$$

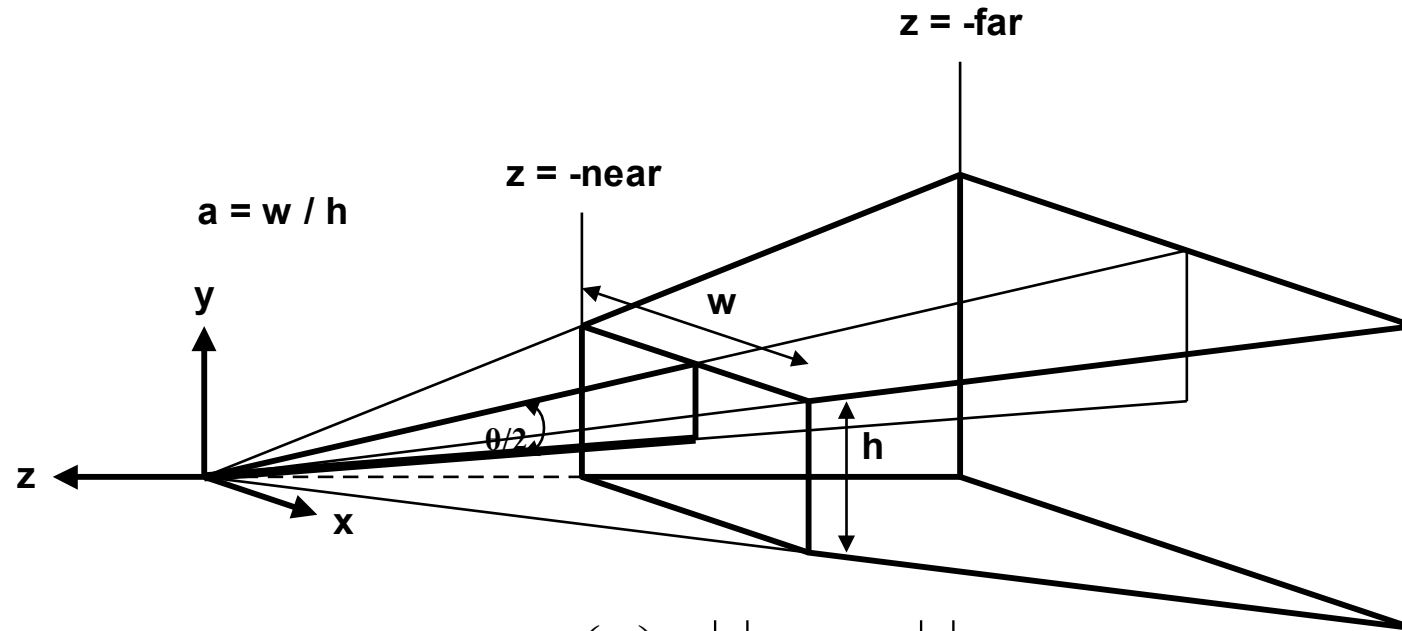
Perspective Transformation Matrix

Another way

The matrix to perform **perspective transformation**:

$$\begin{pmatrix} \gamma & 0 & 0 & 0 \\ 0 & \delta & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} \gamma \cdot x \\ \delta \cdot y \\ \alpha \cdot z + \beta \\ -z \end{pmatrix}$$
$$= \begin{pmatrix} \gamma \cdot x / (-z) \\ \delta \cdot y / (-z) \\ (\alpha \cdot z + \beta) / (-z) \\ 1 \end{pmatrix}$$

Perspective Transformation Matrix - Symmetric

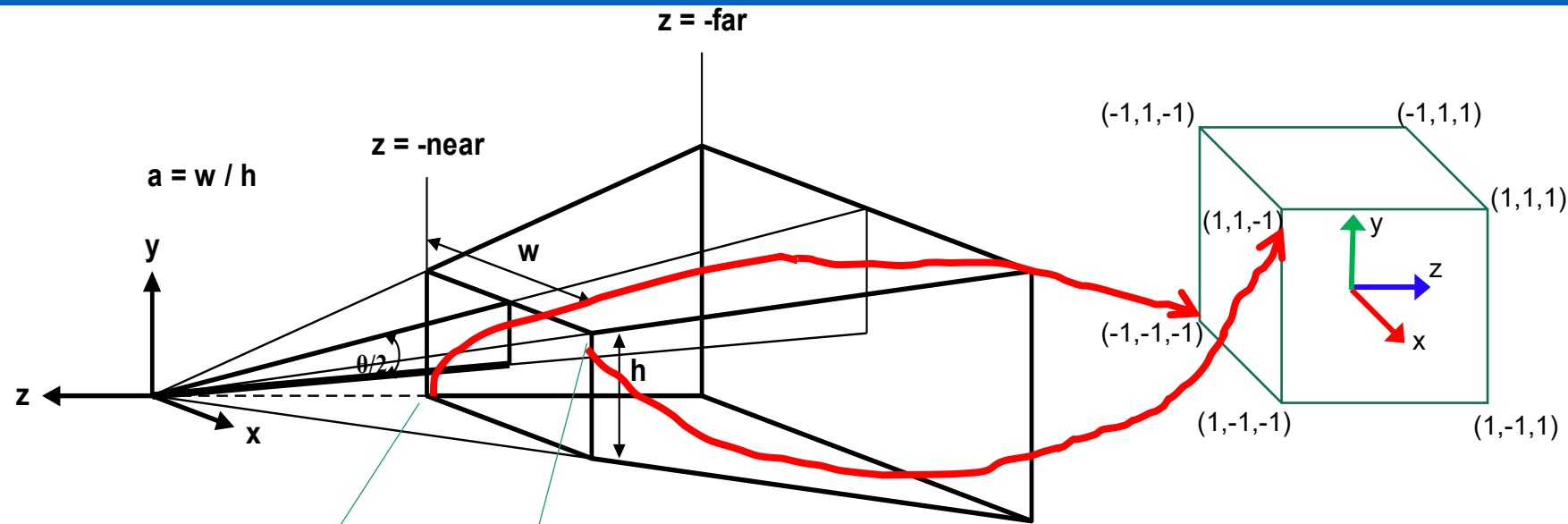


$$c = \cot\left(\frac{\theta}{2}\right) = \frac{|z|}{|y|} \Rightarrow |y| = \frac{|z|}{c}$$

$$a = \frac{w}{h} = \frac{|x|}{|y|} \Rightarrow |x| = a|y| = \frac{a|z|}{c}$$

$$\therefore (x, y, z) \Rightarrow \left(\pm \frac{a|z|}{c}, \pm \frac{|z|}{c}, z \right)$$

Perspective Transformation Matrix - Symmetric



$$\left(-\frac{a|n|}{c}, -\frac{|n|}{c}, -|n| \right) \rightarrow (-1, -1, -1)$$

$$\left(-\frac{a|n|}{c}, \frac{|n|}{c}, -|n| \right) \rightarrow (-1, 1, -1)$$

$$\left(\frac{a|n|}{c}, -\frac{|n|}{c}, -|n| \right) \rightarrow (1, -1, -1)$$

$$\left(\frac{a|n|}{c}, \frac{|n|}{c}, -|n| \right) \rightarrow (1, 1, -1)$$

$$\left(-\frac{af}{c}, -\frac{f}{c}, -f \right) \rightarrow (-1, -1, 1)$$

$$\left(-\frac{af}{c}, \frac{f}{c}, -f \right) \rightarrow (-1, 1, 1)$$

$$\left(\frac{af}{c}, -\frac{f}{c}, -f \right) \rightarrow (1, -1, 1)$$

$$\left(\frac{af}{c}, \frac{f}{c}, -f \right) \rightarrow (1, 1, 1)$$

all f are $|f|$

Perspective Transformation Matrix - Symmetric

$$\left(-\frac{an}{c}, -\frac{n}{c}, -n\right) \rightarrow (-1, -1, -1)$$

$$\begin{pmatrix} \gamma & 0 & 0 & 0 \\ 0 & \delta & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} -\frac{an}{c} \\ -\frac{n}{c} \\ -n \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -\frac{\gamma an}{c} \\ -\frac{\delta n}{c} \\ -\alpha n + \beta \\ n \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -\frac{\gamma a}{c} \\ -\frac{\delta}{c} \\ -\alpha n + \beta \\ n \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\Rightarrow \gamma = \frac{c}{a}$$

$$\Rightarrow \delta = c$$

$$\Rightarrow -\alpha n + \beta = -n$$

Perspective Transformation Matrix - Symmetric

$$\left(-\frac{af}{c}, -\frac{f}{c}, -f\right) \rightarrow (-1, -1, 1)$$

$$\begin{pmatrix} \gamma & 0 & 0 & 0 \\ 0 & \delta & 0 & 0 \\ 0 & 0 & \alpha & \beta \\ 0 & 0 & -1 & 0 \end{pmatrix} \cdot \begin{pmatrix} -\frac{af}{c} \\ -\frac{f}{c} \\ c \\ -f \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -\frac{\gamma af}{c} \\ -\frac{\delta f}{c} \\ -\alpha f + \beta \\ f \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ -1 \\ 1 \end{pmatrix}$$

$$\Leftrightarrow \begin{pmatrix} -\frac{\gamma a}{c} \\ -\frac{\delta}{c} \\ -\alpha f + \beta \\ f \\ 1 \end{pmatrix} = \begin{pmatrix} -1 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow -\alpha f + \beta = f$$

$$\because -\alpha n + \beta = -n$$

$$\therefore \alpha = \frac{f+n}{n-f}$$

$$\therefore \beta = \frac{2fn}{n-f}$$

Perspective Transformation Matrix - Symmetric

The matrix to perform *perspective transformation*:

$$\begin{pmatrix} \frac{c}{a} & 0 & 0 & 0 \\ 0 & c & 0 & 0 \\ 0 & 0 & \frac{f+n}{n-f} & \frac{2fn}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Perspective projection

- ❑ Using the Frustum parameters, and considering it a symmetric one
- ❑ Final matrix

$$\begin{bmatrix} \frac{2n}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2n}{t-b} & 0 & 0 \\ 0 & 0 & \frac{f+n}{n-f} & \frac{2fn}{n-f} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

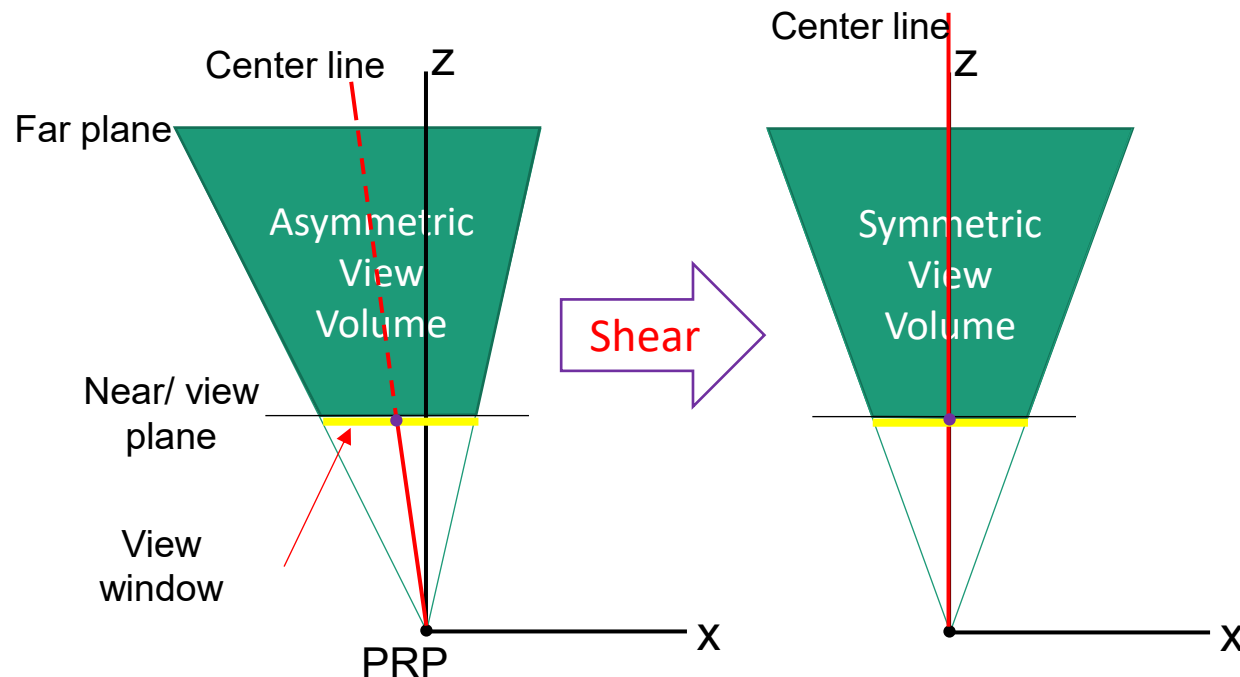
$$\begin{bmatrix} \frac{-2n}{r-l} & 0 & 0 & 0 \\ 0 & \frac{-2n}{t-b} & 0 & 0 \\ 0 & 0 & \frac{f+n}{n-f} & \frac{-2fn}{n-f} \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

Baker Book

This is also true, here all n and f are absolute values

Perspective projection

- ❑ The view frustum may not be centered along the view vector, so it needs one more step, first shear the window.



$$\begin{pmatrix} 1 & 0 & a & 0 \\ 0 & 1 & b & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Shear matrix

Shear

$$\begin{aligned} x' &= x + az \\ y' &= y + bz \end{aligned}$$

$$((r+l)/2, (t+b)/2, -n) \longrightarrow (0, 0, -n)$$

$$\begin{aligned} a &= (r+l)/2n \\ b &= (t+b)/2n \end{aligned}$$

Perspective projection

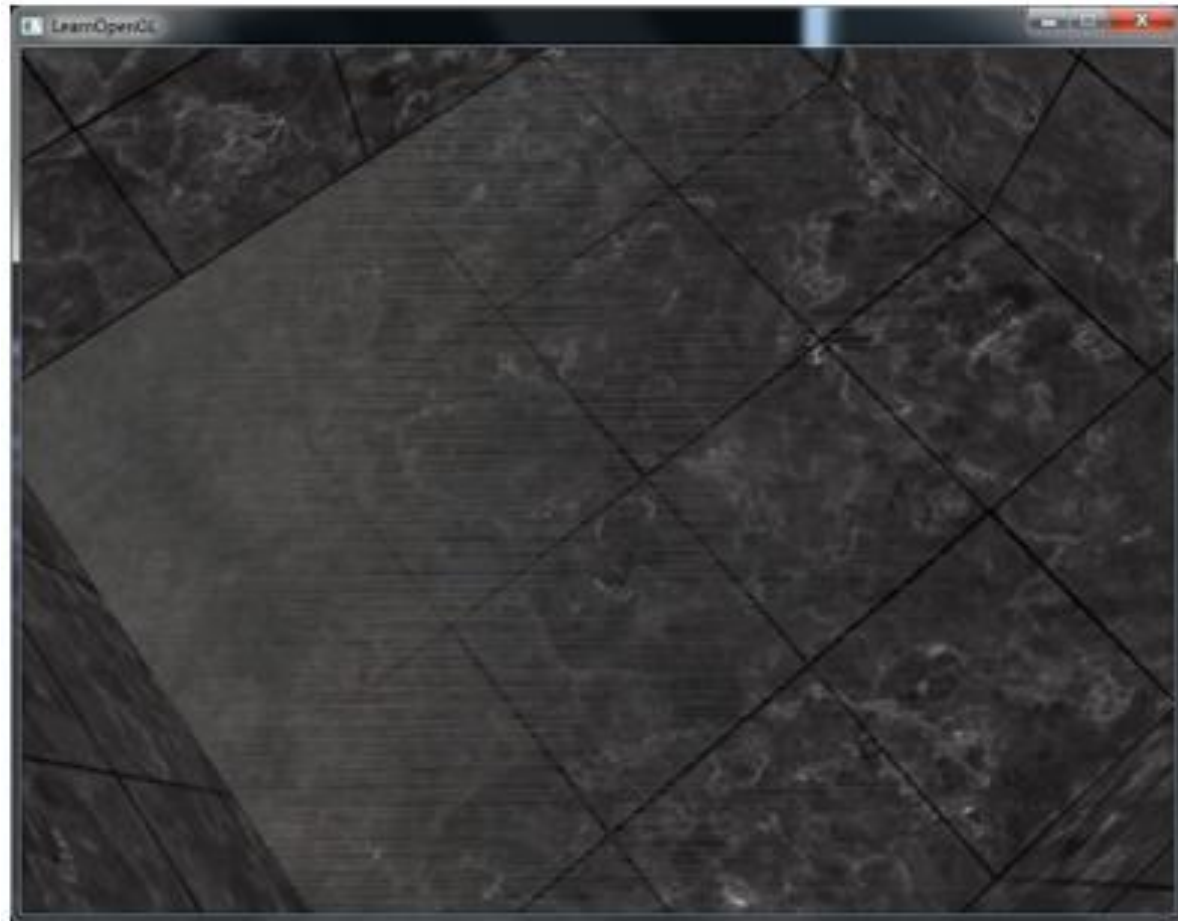
n	-10		alpha	-1.5					
f	-50		beta	-25					
z_eye	z_pers	z_ndcs	p_divisor						
-10	-10	-1	10						
-12	-7	-0.58333	12						
-14	-4	-0.28571	14						
-16	-1	-0.0625	16						
-18	2	0.111111	18						
-20	5	0.25	20						
-22	8	0.363636	22						
-24	11	0.458333	24						
-26	14	0.538462	26						
-28	17	0.607143	28						
-30	20	0.666667	30						
-32	23	0.71875	32						
-34	26	0.764706	34						
-36	29	0.805556	36						
-38	32	0.842105	38						
-40	35	0.875	40						
-42	38	0.904762	42						
-44	41	0.931818	44						
-46	44	0.956522	46						
-48	47	0.979167	48						
-50	50	1	50						

The figure consists of two vertically stacked line plots sharing a common x-axis labeled 'z_eye' ranging from -60 to 0. The top plot shows 'z_pers' (blue line) increasing linearly from -10 at z_eye = -50 to 50 at z_eye = 0. The bottom plot shows 'z_ndcs' (orange line) increasing non-linearly from -1 at z_eye = -50 to 1 at z_eye = 0.

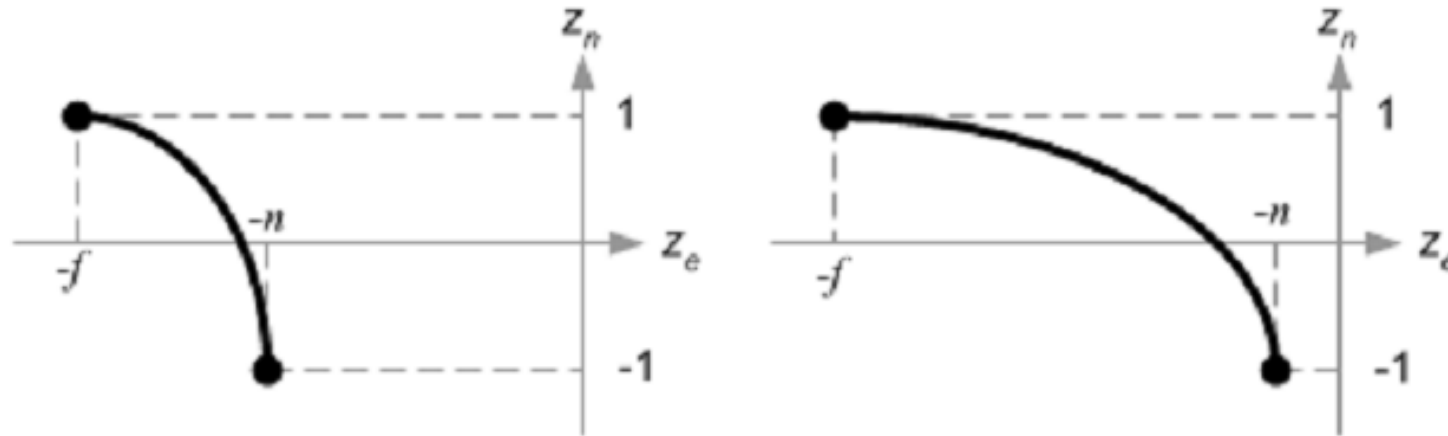
Z-Fighting Problem

- ❑ A common visual artifact might occur when two planes are closely aligned to each
 - The depth buffer does not have enough precision to figure out which one is in front of the other.

$$z' = -d \cdot \alpha - \frac{d \cdot \beta}{z}$$



Z-Fighting Problem



Comparison of Depth Buffer Precisions

$$z' = -d \cdot \alpha - \frac{d \cdot \beta}{z}$$

z	z'
97	0.9993752
98	0.9995877
99	0.9997959

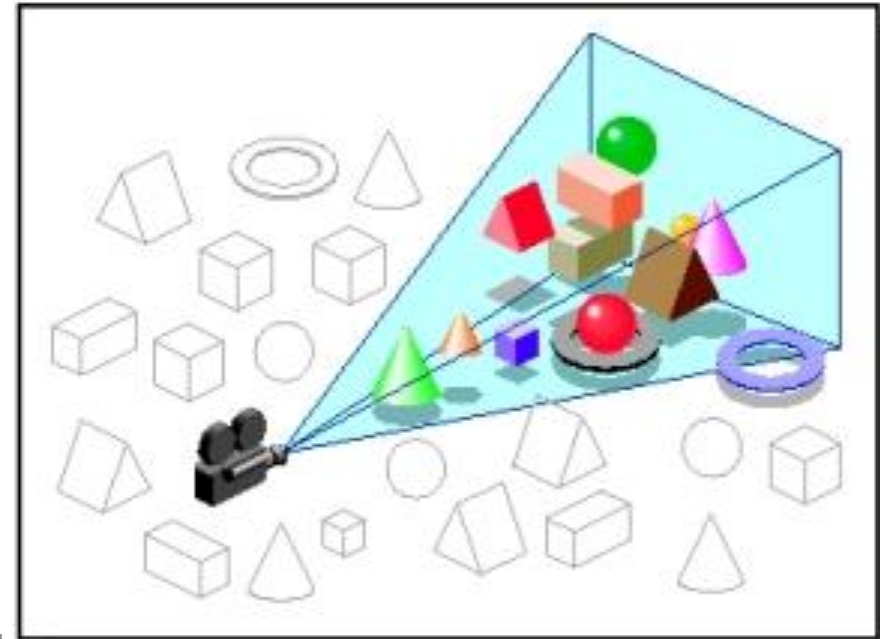
- ❑ N=1, F=100, z' ranges from -1 to +1
- ❑ Prevention
 - *set the near plane as far as possible*
 - *never place objects too close to each other in a way that some of them closely overlap*
 - *use a higher precision depth buffer*

WCS, VCS, NDCS and projection

- ❑ You are given info about
 - P_0, P, V in WCS
 - $d, f, a=h/w, \text{fovy}$
- ❑ Let the apex of the pyramidal object in the scene $(1,2,1)_{\text{WCS}}$
- ❑ Find the NDCS value of the apex

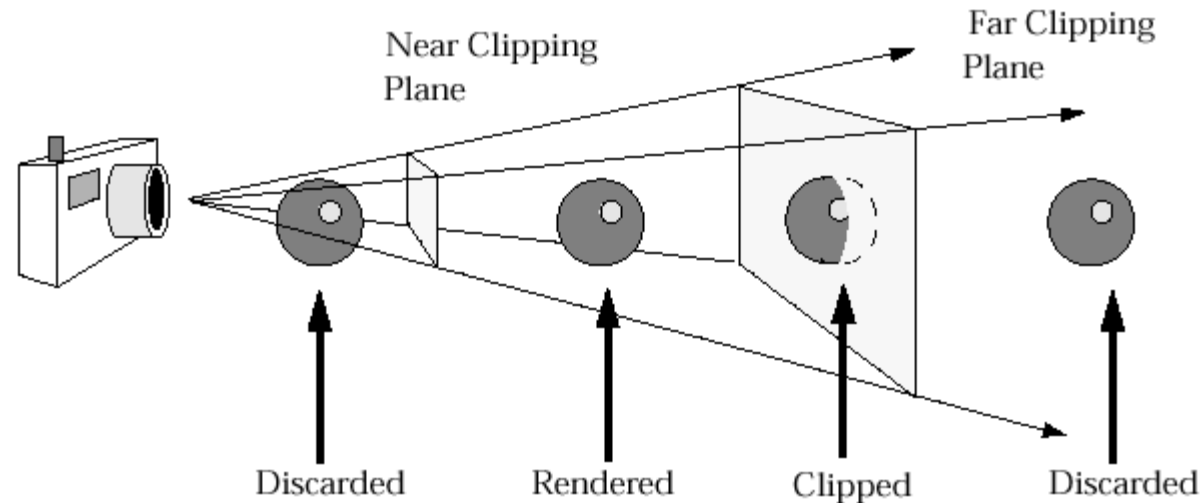
3-D Clipping

- ❑ Clipping removes objects that will not be visible
- ❑ The point of this is to remove computational effort
- ❑ Achieved in two basic steps
 - Discard objects that can't be viewed
 - i.e. objects that are behind the camera, outside the field of view, or too far away
 - Clip objects that intersect with any clipping plane



3-D Clipping

- ❑ Discarding objects that cannot possibly be seen involves comparing an objects bounding box/sphere against the dimensions of the view volume
 - Can be done before or after projection



When Do We Clip?

- ❑ We perform clipping after normalisation are done
- ❑ So, we have the following:

$$\begin{bmatrix} x_h \\ y_h \\ z_h \\ h \end{bmatrix} = M_{Norm} \cdot \begin{bmatrix} x_e \\ y_e \\ z_e \\ w_e \end{bmatrix}$$

- ❑ We apply all clipping to these homogeneous coordinates

How to Clip

- Because we have a normalised clipping volume we can test for these regions as follows:

$$-1 \leq \frac{x_h}{h} \leq 1 \quad -1 \leq \frac{y_h}{h} \leq 1 \quad -1 \leq \frac{z_h}{h} \leq 1$$

- Rearranging these we get:

$$-h \leq x_h \leq h \quad -h \leq y_h \leq h \quad -h \leq z_h \leq h \quad \text{if } h > 0$$

$$h \leq x_h \leq -h \quad h \leq y_h \leq -h \quad h \leq z_h \leq -h \quad \text{if } h < 0$$

- Objects that are partially within the viewing volume need to be clipped – just like the 2D case